

The k -Cap Process on Geometric Random Graphs

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Abstract

The k -cap (or k -winners-take-all) process on a graph works as follows: in each iteration, exactly k vertices of the graph are in the cap (i.e., winners); the next round winners are the vertices that have the highest total degree to the current winners.

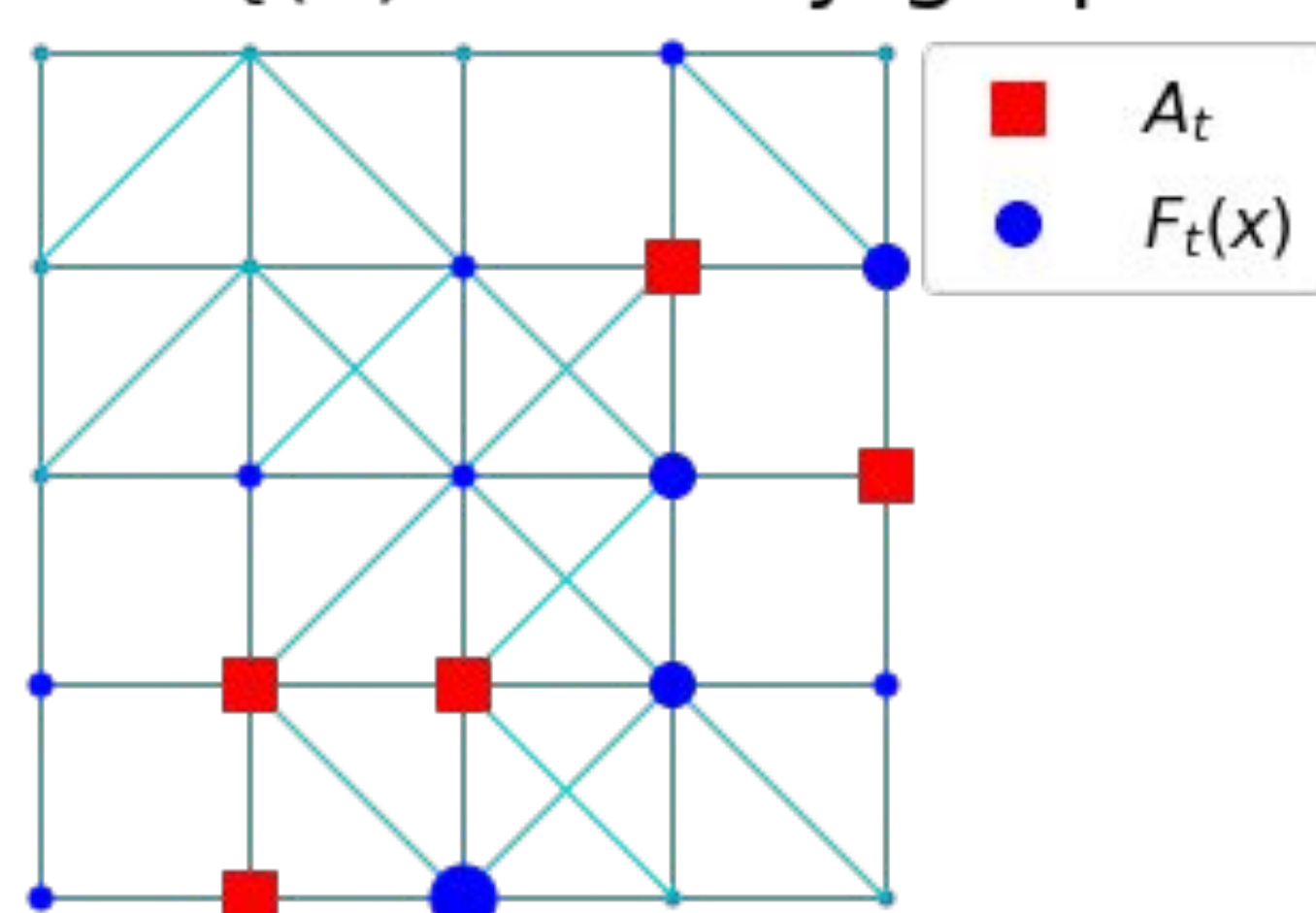
This natural process is a simple model of firing activity in the brain. We study its convergence on geometric random graphs, revealing rather surprising behavior.

Introduction

Definition of the k -cap Process: Given a graph G with n vertices $\{1, 2, \dots, n\}$, at a timestep $t > 0$, let A_{t-1} be the set of k vertices with the **largest degree** in A_t (with ties broken randomly). We define the input F_t as a function of the edges $e_{y,x}$ to x :

$$F_t(x) = \sum_{y \in A_t} e_{y,x}$$

$F_t(x)$ on a toy graph



Motivating Questions:

- Does this process converge to a small subset of the vertices of G ?
- If so, how quickly does it converge?
- How does the structure of A_t evolve as $t \rightarrow \infty$?

Setting: Geometric Random Graphs

- Embed each vertex in a *hidden variable space*.
- If two vertices are closer in the space, they are more likely to be connected by an edge

Assumption: edge probability is proportional to 1-D Gaussian function with parameters $\sigma=1/k$, $n > k^{3+\epsilon}$.

Discrete Process

A_0 chosen uniformly at random from $[0, 1]$.
Poisson Clumping: Given uniform random points, some regions will have a higher density.

Expected input and $p(x)$ at $t=0$

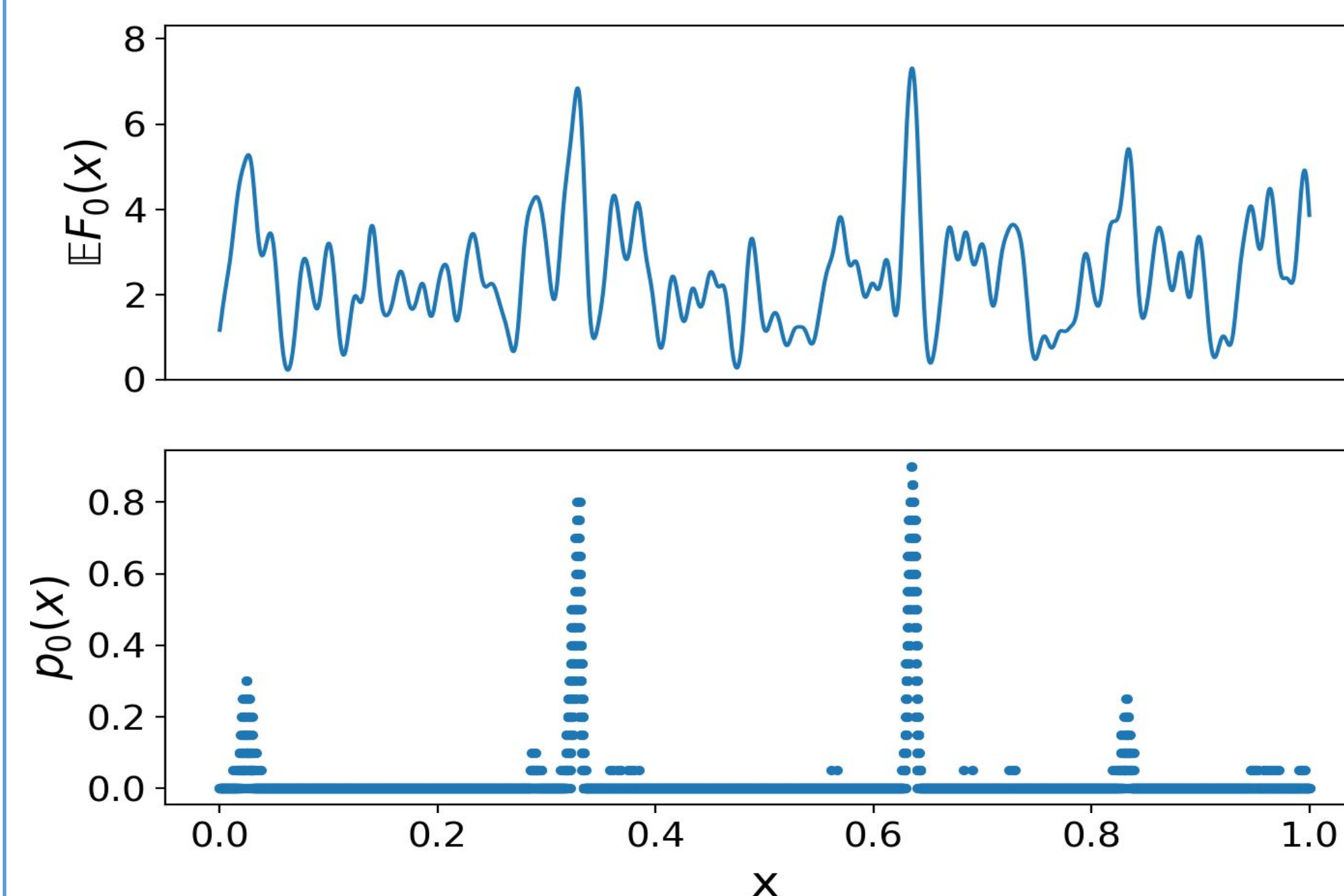


Fig.: Simulation results at $t=0$. (TOP) Expected degree to x from A_0 (BOTTOM) Probability that x is in the top k .

Theorem: At step 1, WHP A_t can be covered by $O(\ln k)$ intervals of size $O(\sigma \ln \ln k)$.

Analysis at $t > 1$

Expected input and $p(x)$ at $t=4$

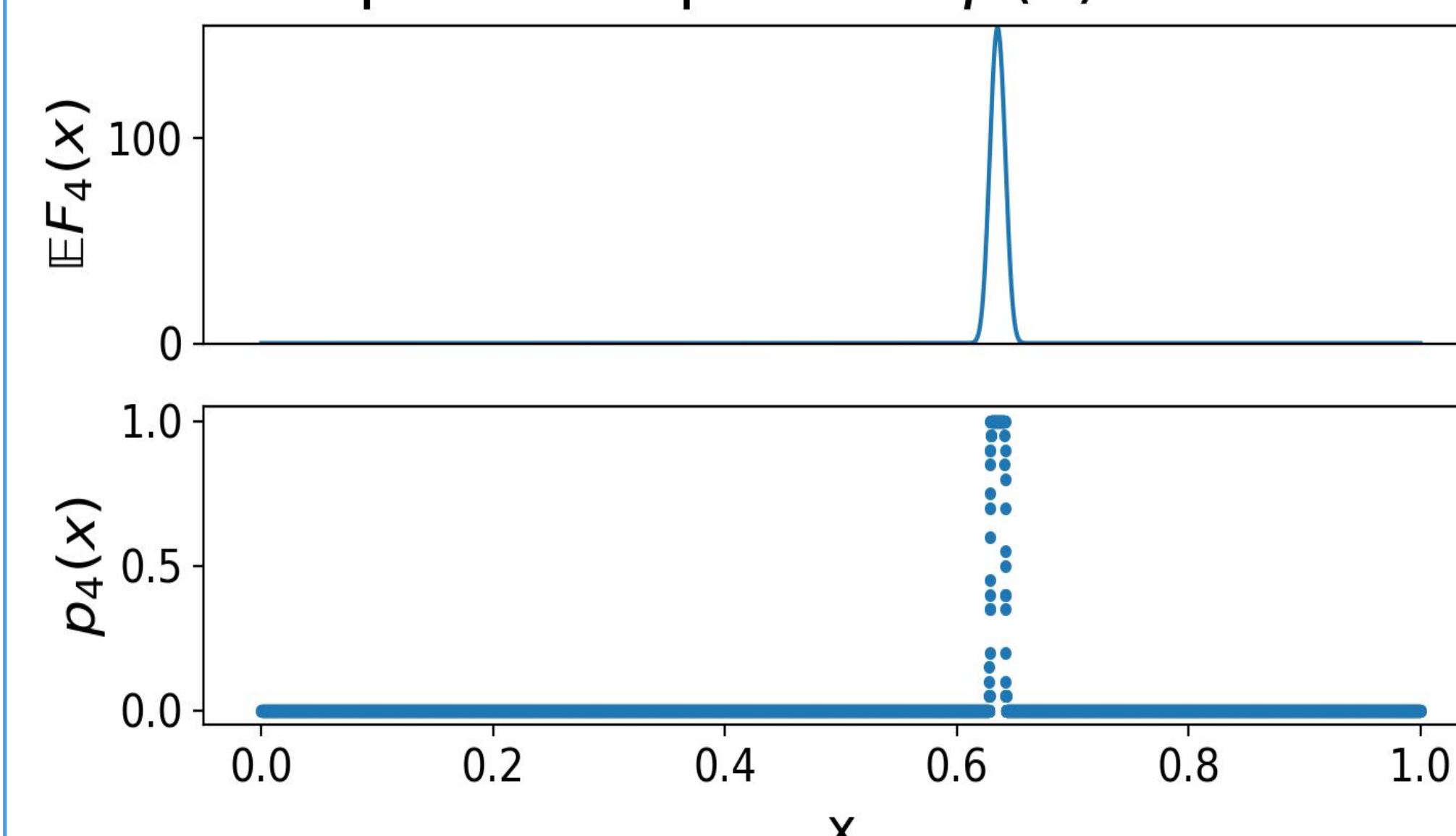
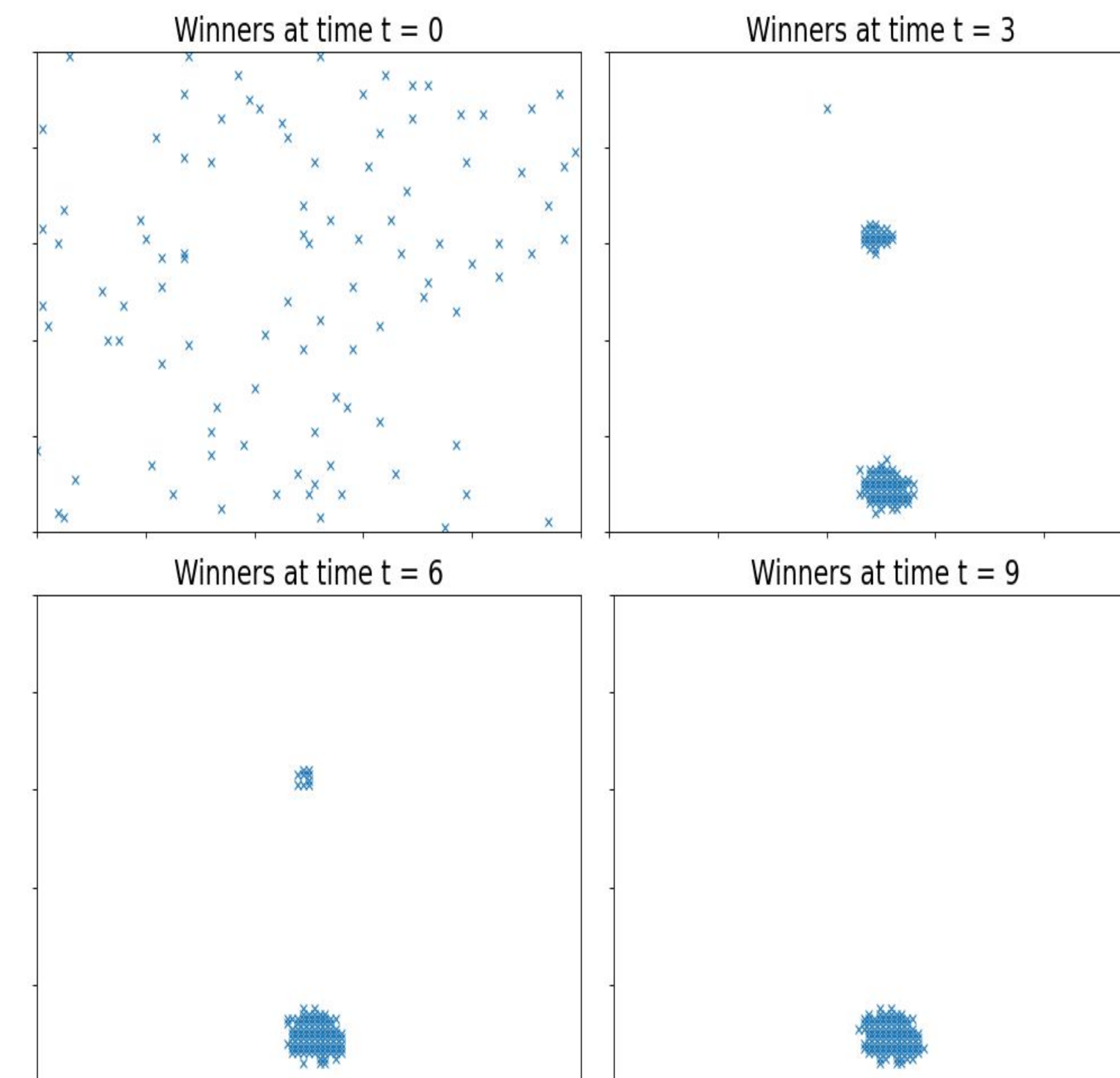


Fig: Simulation results at time $t=4$; showing the expected input to a vertex x and the probability that x is in the next firing set, plotted against the hidden variable.

Theorem: After $\text{polylog}(k)$ steps, with high probability, the winners at t can be covered by a **single** interval of size $o\left(\sigma \sqrt{\frac{\ln k}{k}}\right)$

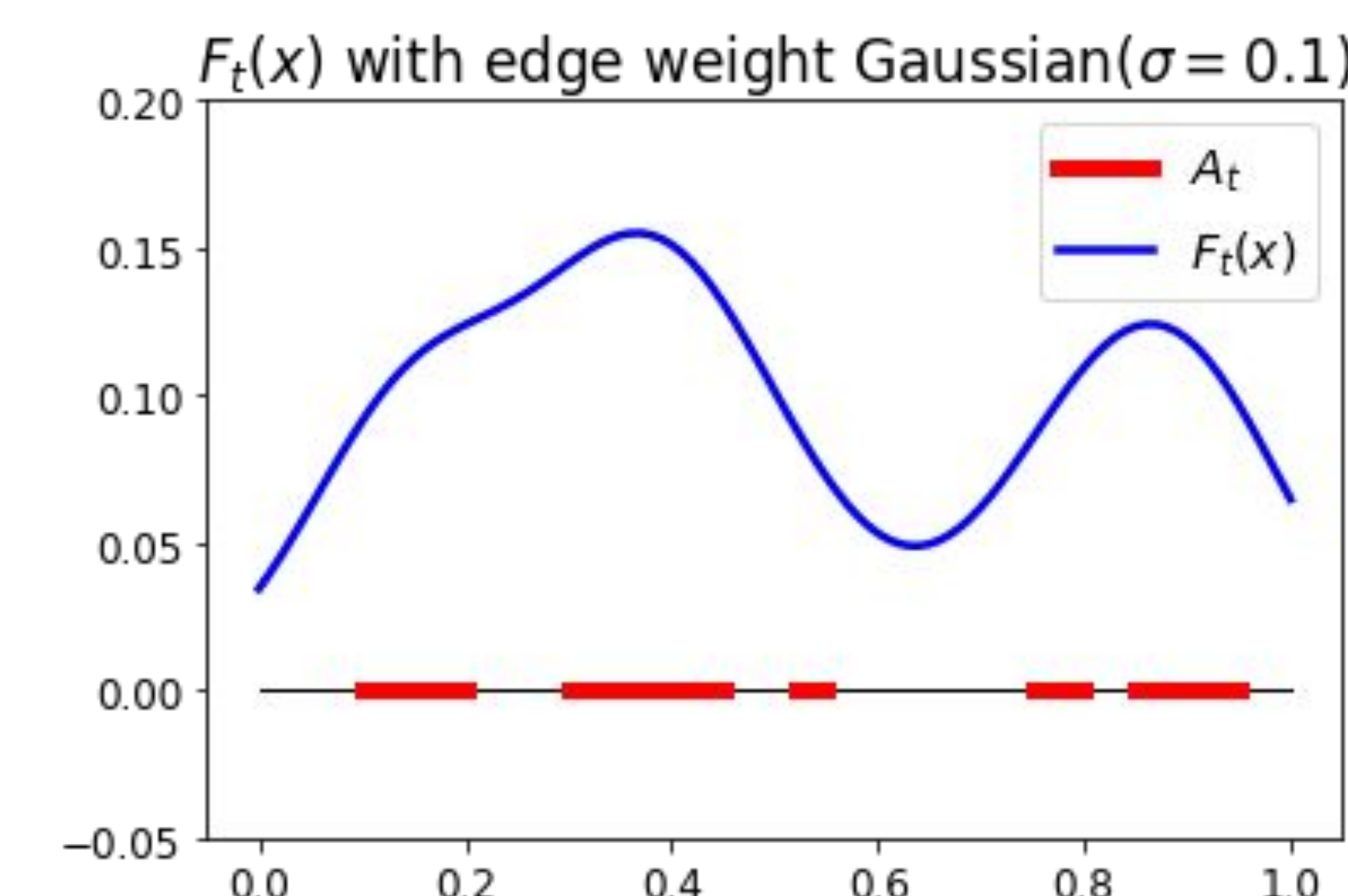
Simulation on a graph with hidden variables in 2D
Parameters: $n=10000$ vertices, $k=100$ cap size



Continuous Limit: α -cap Process

Consider how the process evolves as n (the number of vertices in the graph) approaches ∞ .

Firing set: $A_t \subset [0, 1]$ is a union of intervals with measure α . An example of $F_t(x)$ is shown below:



Definition: Let $\alpha = |A_0|$ and g be a real integrable function. For a finite union of intervals A_t , define:

$$F_t(x) = \int_0^1 A_t(y) g(y-x) dy$$

$$A_{t+1}(x) = \begin{cases} 0 & F_t(x) < C_{t+1} \\ 1 & F_t(x) \geq C_{t+1} \end{cases}$$

where $C_{t+1} \in [0, 1]$ is the solution to $\int_0^1 A_{t+1}(x) dx = \alpha$.

We showed this converges to a **single interval** of measure α .

Theorem 1. Let A_0 be a finite set of intervals on $[0, 1]$ and g be the edge probability function. For any even, nonnegative, integrable function $g : [0, 1] \rightarrow \mathbb{R}_+$ with $g'(x) < 0$ for all $x > 0$, the α -cap process converges to a single interval of width α . Moreover, the number of steps to convergence is

$$O\left(\frac{\max_{[0,1]} |g'(x)|}{\min_{[\frac{\alpha}{8}, 1]} |g'(x)|}\right).$$

Motivation from the Brain

Graphs and the Brain:

- We model the brain as a random graph, where neurons are vertices and synapses are edges.
- Neuronal connections are **not random**; probability of connection depends on distance in space.
- Geometric graphs have been used to model graphs of neurons;
 - Neuron position and characteristics can be represented with the hidden variable.

k -Cap and the Brain:

- The **firing pattern** of neurons behaves similarly to k -cap;
 - **Inhibition** prevents too many neurons from firing at once.
- **Plasticity** strengthens connections between adjacent neurons.
 - Adding plasticity to the k -cap process leads to convergence on directed random graphs.

Future Directions:

- Extend both continuous and discrete processes to higher dimensional hidden variable spaces.
- Other graph models - e.g., convergence on $G(n, p)$

References

- Reid, Mirabel, and Santosh S. Vempala. "The k -Cap Process on Geometric Random Graphs." *arXiv preprint arXiv:2203.12680* (2022).
- Bullmore, Ed, and Olaf Sporns. "Complex brain networks: graph theoretical analysis of structural and functional systems." Papadimitriou, Christos H., et al. "Brain computation by assemblies of neurons."

Simulation code available at

<https://github.com/mirabelreid/Assemblies-Simulations>